

# Rigid but not infinitesimally rigid compact complex manifolds

joint work with I. Bauer (Bayreuth)

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Geometria in Bicocca

Milano, September 16<sup>th</sup>, 2019



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# Rigid compact complex manifolds

## Definition

A compact complex manifold  $M$  is *rigid* if for each deformation of  $M$ ,  $f: (\mathfrak{X}, M) \rightarrow (B, b_0)$  there is an open neighbourhood  $U \subset B$  of  $b_0$  such that  $M_t := f^{-1}(t) \cong M$  for all  $t \in U$ .

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The situation in higher dimension is much more complicated: for example the Hirzebruch surface  $\mathbb{F}_2$  is not rigid and homeomorphic to the rigid surface  $\mathbb{P}_{\mathbb{C}}^1 \times \mathbb{P}_{\mathbb{C}}^1$ .



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How do we check the rigidity of a manifold?



# The Kuranishi family

Let  $M$  be a compact complex manifold.

Kuranishi constructed a deformation  $\pi: (\mathcal{X}, M) \rightarrow (\text{Def}(M), 0)$  of  $M$  where  $(\text{Def}(M), 0)$  is a germ of analytic subspace of the vector space<sup>1</sup>  $H^1(M, \Theta)$ , inverse image of the origin under a local holomorphic map  $k: H^1(M, \Theta) \rightarrow H^2(M, \Theta)$  whose differential vanishes<sup>2</sup> at the origin.

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<sup>1</sup>Here  $\Theta$  is the sheaf of holomorphic vector fields on  $M$ .

<sup>2</sup>Then  $H^1(M, \Theta)$  is the Zariski tangent space of  $(\text{Def}(M), 0)$ .

In particular  $(\text{Def}(M), 0)$  is smooth if and only if  $k = 0$ , in which case we say that  $M$  has *unobstructed deformations*.





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## Theorem (Kuranishi)

*The Kuranishi family is semiuniversal, and universal if  $H^0(M, \Theta) = 0$ .*

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## Theorem (Kuranishi)

*The Kuranishi family is semiuniversal, and universal if  $H^0(M, \Theta) = 0$ . The quadratic term in the Taylor development of  $k$  is given by the bilinear map  $H^1(M, \Theta) \times H^1(M, \Theta) \rightarrow H^2(M, \Theta)$  called Schouten bracket, which is the composition of cup product followed by Lie bracket of vector fields.*

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## Corollary (Kuranishi's criterion for rigidity)

$M$  *infinitesimally rigid*  $\Rightarrow$   $M$  *rigid*



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## Corollary (Kuranishi's criterion for rigidity)

$$M \text{ infinitesimally rigid} \Rightarrow M \text{ rigid}$$

In particular  $\mathbb{P}_{\mathbb{C}}^1 \times \mathbb{P}_{\mathbb{C}}^1$  is (infinitesimally) rigid.



# Morrow-Kodaira's Problem

Morrow and Kodaira asked if the converse implication also hold<sup>3</sup>:

**THEOREM 3.2.** If  $H^1(M, \Theta) = 0$ , then  $M$  is rigid. We will give a proof of this using elementary methods. We have the following:

**PROBLEM.** Find an example of an  $M$  which is rigid, but  $H^1(M, \Theta) \neq 0$ .  
(Not easy?)

**REMARK.**  $\mathbb{P}^n$  is rigid. For  $n \geq 2$  the only known proof is to show  $H^1(\mathbb{P}^n, \Theta) = 0$  [Bott (1957)]. Let us proceed to the proof.

A solution of the M-K Problem is a manifold  $M$  such that  $\text{Def}(M)$  is a *fat* point, a *singular* point.

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<sup>3</sup>This is a screenshot of the book *Complex Manifolds* by James Morrow and Kunihiko Kodaira (1971), *Holt, Rinehart and Winston, Inc.*



# The main result

## Theorem

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$$K_{S_n}^2 = 2(n-3)^2, \quad p_g(S_n) = \left(\frac{n}{2} - 2\right) \left(\frac{n}{2} - 1\right),$$

such that  $S_n$  is rigid, but not infinitesimally rigid:  $h^1(S_n, \Theta) = 6$ .



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The canonical models of these surfaces have exactly 6 singular points, all nodes<sup>4</sup>. The hard part is proving their rigidity, since Kuranishi's rigidity criterion fails.

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<sup>4</sup>A node is a singular point locally isomorphic to the quotient of a 2-dimensional disc by  $p \mapsto -p$ .





# Generalization to higher dimension

## Lemma

Let  $M, N$  be compact complex manifolds, such that

$$h^0(M, \Theta)h^1(N, \mathcal{O}) = h^0(N, \Theta)h^1(M, \mathcal{O}) = 0.$$

Then  $\text{Def}(M \times N) = \text{Def}(M) \times \text{Def}(N)$ .

Then, if  $M$  is a regular surface of general type solving the M-K Problem and  $N$  is a rigid manifold, by Künneth formula  $M \times N$  is a solution too.



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Then, if  $M$  is a regular surface of general type solving the M-K Problem and  $N$  is a rigid manifold, by Künneth formula  $M \times N$  is a solution too. Using some known rigid manifolds<sup>5</sup> we obtain

## Theorem

There are rigid manifolds of dimension  $d$  and Kodaira dimension  $\kappa$  that are not infinitesimally rigid for all possible pairs  $(d, \kappa)$  with  $d \geq 5$  and  $\kappa \neq 0, 1, 3$  and for  $(d, \kappa) = (3, -\infty), (4, -\infty), (4, 4)$ .

<sup>5</sup>listed in Ingrid Bauer and Fabrizio Catanese, *On rigid compact complex surfaces and manifolds*, *Adv. Math.* **333**, 620–669 (2018).

We need  $M$  rigid: these are rare manifolds.

Theorem (Ingrid Bauer and Fabrizio Catanese, *On rigid compact complex surfaces and manifolds*, *Adv. Math.* **333**, 620–669 (2018).)

Let  $M$  be a smooth compact complex surface, which is rigid. Then either

- 1  $M$  is a minimal surface of general type, or
- 2  $M$  is a Del Pezzo surface of degree  $d \geq 5$
- 3  $M$  is an Inoue surface of type  $S_M$  or  $S_{N,p,q,r}^-$

Rigid Del Pezzo and Inoue surfaces are infinitesimally rigid, so every surface solving M-K Problem has Kodaira dimension 2.

The minimal model of any rigid surface of general type whose canonical model is singular does the job.



# We need $M$ with obstructed deformations

We need  $\dim M \geq 2$ . Several examples of manifolds  $M$  of dimension 2 with obstructed deformations are now known.



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Burns and Wahl<sup>6</sup> show how to associate to each smooth rational curve  $E$  with  $E^2 = -2$  in a complex surface  $M$  a 1-dimensional subspace  $H_E^1(M)$  of  $H^1(M, \Theta)$ .

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Note that in particular if  $M$  is the minimal resolution of the singularities of a *nodal* surface<sup>7</sup>,  $M$  can't be infinitesimally rigid.

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Note that in particular if  $M$  is the minimal resolution of the singularities of a nodal surface<sup>7</sup>,  $M$  can't be infinitesimally rigid.

A necessary condition for  $M$  to be rigid is that it is obstructed along this line:  $H_E^1(M) \not\subset \text{Def}(M)$ . A way to check it has been provided by Kas<sup>8</sup>.

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<sup>8</sup>Arnold Kas, *Ordinary double points and obstructed surfaces*, *Topology* **16** (1), 51 – 64 (1977).



# The Kas maps

Let now  $X$  be a compact complex surface with a node  $\nu$ ,  $M \rightarrow X$  be the minimal resolution of singularities of  $M$ , let  $E$  be exceptional curve mapping to  $\nu$  and let  $\theta$  be a generator of  $H_E^1(M) \subset H^1(M, \Theta)$ .





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Then we can write

$$k(t\theta) = \alpha_\nu t^2 + O(3) \in H^2(M, \Theta),$$

where, by Serre duality we can see  $\alpha_\nu$  as a map  $\alpha_\nu: H^0(M, \Omega^1 \otimes \Omega^2) \rightarrow \mathbb{C}$ . A neighbourhood of  $\nu$  in  $X$  is the quotient of a disc  $\Delta \subset \mathbb{C}^2$  by the involution  $(z_1, z_2) \mapsto (-z_1, -z_2)$ .

Pulling-back we get an inclusion  $H^0(M, \Omega^1 \otimes \Omega^2) \subset H^0(\Delta, \Omega^1 \otimes \Omega^2)^+$  allowing to write locally every  $\eta \in H^0(M, \Omega^1 \otimes \Omega^2)$  as

$$\eta = (f_1 dz_1 + f_2 dz_2) \otimes (dz_1 \wedge dz_2)$$

Then Kas shows

$$\alpha_\nu(\eta) = \left( \frac{\partial f_2}{\partial z_1} - \frac{\partial f_1}{\partial z_2} \right) (0, 0).$$



# Interesting examples with obstructed deformations

- 1 Burns and Wahl construct<sup>9</sup> many examples of smooth surfaces with obstructed deformations by resolving the singularities of certain nodal hypersurfaces in  $\mathbb{P}^3$ .
- 2 Catanese<sup>10</sup> constructs surfaces  $M$  whose Kuranishi family  $\text{Def}(M)$  is *everywhere nonreduced* by resolving the singularities of certain quotients  $(C_1 \times C_2)/G$  ( $C_i$  curves,  $G$  finite group) with rational double points.

Still, all these examples are not rigid.

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<sup>9</sup>D. M. Burns Jr. and Jonathan M. Wahl, *Local contributions to global deformations of surfaces*, *Invent. Math.* **26**, 67 – 88 (1974).

<sup>10</sup>Fabrizio Catanese, *Everywhere nonreduced moduli spaces*, *Invent. Math.* **98** (2), 293 – 310 (1989).



# Strategy to the proof of the main theorem

Rigid manifolds are rare. I know a short list of examples of rigid surfaces of general type, all infinitesimally rigid: ball quotients, irreducible bi-disk quotients, Beauville surfaces, Mostow-Siu surfaces, some Kodaira fibrations constructed by Catanese and Rollenske.

## Example (Beauville surfaces)

Consider two projective curves  $C_1, C_2$ , a finite group  $G$  and two injective homomorphisms  $G \subset \text{Aut}(C_i)$ .

Assume that the induced action  $g(x, y) = (gx, gy)$  of  $G$  on  $C_1 \times C_2$  is free. Then  $M := (C_1 \times C_2)/G$  is smooth.

If  $(C_i, G)$  are *triangle curves*<sup>a</sup>, then  $M$  is a *Beauville surface*.

<sup>a</sup>i.e.  $C_i/G \cong \mathbb{P}^1$  and  $p_i: C_i \rightarrow C_i/G$  has exactly three branching points.



## Catanese's lemma

Lemma (Fabrizio Catanese, *Everywhere nonreduced moduli spaces*, *Invent. Math.* **98** (2), 293 – 310 (1989))

Let  $Z$  be a smooth algebraic surface and  $G$  a finite group acting on it freely in codimension 1. Set  $p: Z \rightarrow X := Z/G$ .  
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### Corollary

Consider two projective curves  $C_1, C_2$ , a finite group  $G$  and two injective homomorphisms  $G \subset \text{Aut}(C_i)$ . Set  $X := (C_1 \times C_2)/G$ .  
If  $(C_i, G)$  are triangle curves, then  $H^1(X, \Theta) = 0$ .



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This implies that Beauville surfaces are infinitesimally rigid.

Note however that here  $G$  may act not freely, and then  $X$  has isolated singularities. Then the minimal resolution  $M$  of the singularities of  $X$  may still be neither rigid nor infinitesimally rigid.



# A criterion to prove rigidity

## Theorem

Let  $M$  be the minimal res. of the sing. of a nodal surface  $X$ . Assume that

- 1  $H^1(X, \Theta) = 0$ ;
- 2 the maps  $\alpha_{\nu_i}$  associated to the nodes  $\nu_i$  of  $X$  locally described in (1) are linearly independent in  $H^0(M, \Omega^1 \otimes \Omega^2)^\vee$ .

Then  $M$  is rigid and  $h^1(M, \Theta)$  equals the number of nodes of  $X$ .





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## Sketch of the proof.

By condition 1 and a remark of Pinkham<sup>a</sup>  $H^1(M, \Theta) \cong \bigoplus H_{E_i}^1(M)$ .

Choose  $0 \neq \theta_i \in H_{E_i}^1(M)$ : they form a basis of  $H^1(M, \Theta)$ . Then  $k(\sum t_i \theta_i) = \sum_1^r t_i^2 \alpha_{\nu_i} + O(3)$ . The rigidity follows now by condition 2.  $\square$

<sup>a</sup>Henry Pinkham, *Some local obstructions to deforming global surfaces*, *Nova Acta Leopoldina (N.F.)* **52** (1981), 173-178.

# Strategy of the proof of the main theorem

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We pick two triangle curves  $(C_1, G)$ ,  $(C_2, G)$  for the same finite group, we set  $X := (C_1 \times C_2)/G$  the quotient by the diagonal action.



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Then by Catanese's Lemma the first condition in the rigidity criterion  $H^1(X, \Theta) = 0$  is fulfilled, and we only need to check the second one.



# The Fermat curves

Which triangle curves do the job?

The Fermat curve of degree  $n$ ,  $C := \{\sum_{j=0}^2 x_j^n = 0\} \subset \mathbb{P}_{\mathbb{C}}^2$  admits a natural action of the group  $G \cong (\mathbb{Z}/n\mathbb{Z})^2$ :

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This  $G$ -action has only three orbits of cardinality different by  $n^2$ , all of cardinality  $n$ :

- $C \cap \{x_0 = 0\}$  with stabilizer  $\langle(1, 1)\rangle \cong \mathbb{Z}/n\mathbb{Z}$
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By Hurwitz formula  $C/G \cong \mathbb{P}^1$  so  $(C, G)$  is a triangle curve.





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The surface  $S_n$  is the minimal resolution of the singularities of  $(C_1 \times C_2)/G$ .



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For  $n$  odd, the intersection of these two sets is  $\{(0, 0)\}$ . Then the induced action on  $C_1 \times C_2$  is free:  $S_n$  is a Beauville surface, infinitesimally rigid.

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For  $n$  even the non-trivial elements of  $G$  fixing some points of  $C_1 \times C_2$  are  $(n/2, 0)$ ,  $(0, n/2)$  and  $(n/2, n/2)$ , all of order 2 fixing  $n^2$  points: then  $X$  is a nodal surface with  $3 \cdot 2 \cdot n^2/n^2 = 6$  nodes.



# The proof

We skip the computation of the invariants of  $S_n$ , that is standard.

We need to check if the six maps

$$\alpha_{\nu_i} : H^0(S_n, \Omega^1 \otimes \Omega^2) \rightarrow \mathbb{C}$$

associated to the nodes of  $X$  are linearly independent.

For this we need  $h^0(S_n, \Omega^1 \otimes \Omega^2) \geq 6$ : indeed this excludes the case  $n \leq 4$  giving  $n \geq 8$ .





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When  $h^0(S_n, \Omega^1 \otimes \Omega^2) \geq 6$  may to check the independence of the  $\alpha_{v_i}$  by restricting to a suitable 6-dimensional subspace.



## Decomposition of $H^0(S_n, \Omega^1 \otimes \Omega^2)$

We need a basis of  $H^0(S_n, \Omega^1 \otimes \Omega^2)$  as explicit as possible, in order to be able to compute their image via the Kas map. By

$$\begin{aligned} H^0(S_n, \Omega^1 \otimes \Omega^2) &\cong H^0(C_1 \times C_2, \Omega^1 \otimes \Omega^2)^G \cong \\ &\cong \left( H^0(C_1, \omega_{C_1}^{\otimes 2}) \otimes H^0(C_2, \omega_{C_2}) \right)^G \oplus \left( H^0(C_1, \omega_{C_1}) \otimes H^0(C_2, \omega_{C_2}^{\otimes 2}) \right)^G \cong \\ &\cong \bigoplus_{\chi \in G^*} \left( \left( H^0(\omega_{C_1}^{\otimes 2})^\chi \otimes H^0(\omega_{C_2})^{-\chi} \right) \oplus \left( H^0(\omega_{C_1})^\chi \otimes H^0(\omega_{C_2}^{\otimes 2})^{-\chi} \right) \right) \cong \\ &\cong \bigoplus_{\chi \in G^*} \left( \left( H^0(\omega_{C_1}^{\otimes 2})^\chi \otimes H^0(\omega_{C_1})^{\chi'} \right) \oplus \left( H^0(\omega_{C_1})^\chi \otimes H^0(\omega_{C_1}^{\otimes 2})^{\chi'} \right) \right) \end{aligned}$$

where, writing  $\chi, \chi'$  as a column,  $\chi' := -{}^t A^{-1} \chi$



# Six good characters are enough

## Lemma

Set  $k_0 = k_1 = (1, 0)$ ,  $k_\infty = (0, 1) \in G$ . Assume that there is a set of six characters  $\mathcal{C} := \{\chi_0, \chi'_0, \chi_1, \chi'_1, \chi_\infty, \chi'_\infty\} \subset G^*$ , such that

- 1  $\chi_0 \equiv \chi'_0 \equiv (0, 1)$ ,  $\chi_1 \equiv \chi'_1 \equiv (1, 1)$ ,  $\chi_\infty \equiv \chi'_\infty \equiv (1, 0) \pmod{2}$ ;
- 2  $\forall p \in \{0, 1, \infty\}$ ,  $\chi_p(k_p) \neq \chi'_p(k_p)$ ;
- 3 if  $\chi \in \mathcal{C}$ , then  $H^0(\omega_C)^{(\chi)} \neq \{0\}$ ,  $H^0(\omega_C^{\otimes 2})^{(\chi')} \neq \{0\}$ .

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## Sketch of the proof - part 1

We need to check the linear independence of the six maps  $\alpha_{\nu_j}$ .

We decomposed  $H^0(S_n, \Omega^1 \otimes \Omega^2)$  obtaining addenda of the form  $H^0(\omega_{C_1})^\chi \otimes H^0(\omega_{C_1}^{\otimes 2})^{\chi'}$ . When  $\chi \in \mathcal{C}$ , by condition 3, the addendum is not trivial. Picking one general element in each of them, we get six different elements in  $H^0(S_n, \Omega^1 \otimes \Omega^2)$ .

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## Sketch of the proof - part 2.

Computing explicitly the six Kas maps (1) in them we get the following

$$\begin{array}{lll} (\chi_0(k_0), 1, 0, 0, 0, 0) & (0, 0, \chi_1(k_1), 1, 0, 0) & (0, 0, 0, 0, \chi_\infty(k_\infty), 1) \\ (\chi'_0(k_0), 1, 0, 0, 0, 0) & (0, 0, \chi'_1(k_1), 1, 0, 0) & (0, 0, 0, 0, \chi'_\infty(k_\infty), 1) \end{array}$$



## Decomposition of $p_*\omega_C$

The Fermat triangle curve  $p: C = C_1 \rightarrow \mathbb{P}^1$  is an abelian cover, with group  $G$ . We compute the decomposition of  $p_*\omega_C$  by Pardini's<sup>11</sup> formula

$$\begin{array}{cccccccccccc}
 n-1 & -1 & -1 & -1 & -1 & -1 & -1 & * & -1 & -1 & -1 & -1 & -1 \\
 n-2 & -1 & 0 & -1 & -1 & -1 & * & -1 & -1 & -1 & -1 & -1 \\
 & -1 & 0 & 0 & -1 & -1 & * & -1 & -1 & -1 & -1 & -1 \\
 & -1 & 0 & 0 & 0 & -1 & * & -1 & -1 & -1 & -1 & -1 \\
 & -1 & 0 & 0 & 0 & 0 & * & -1 & -1 & -1 & -1 & -1 \\
 & * & * & * & * & * & * & * & * & * & * & * \\
 & -1 & 0 & 0 & 0 & 0 & * & 0 & -1 & -1 & -1 & -1 \\
 3 & -1 & 0 & 0 & 0 & 0 & * & 0 & 0 & -1 & -1 & -1 \\
 2 & -1 & 0 & 0 & 0 & 0 & * & 0 & 0 & 0 & -1 & -1 \\
 1 & -1 & 0 & 0 & 0 & 0 & * & 0 & 0 & 0 & 0 & -1 \\
 0 & -2 & -1 & -1 & -1 & -1 & * & -1 & -1 & -1 & -1 & -1 \\
 & 0 & 1 & 2 & 3 & & & & & & & n-1
 \end{array}$$

Figure: The degrees of  $(p_*\omega_C)^{(\alpha,\beta)}$

<sup>11</sup>Rita Pardini, *Abelian covers of algebraic varieties*, *J. Reine Angew. Math.* 417, 191-213.



# Decomposition of $p_*\omega_C^{\otimes 2}$

Similarly we compute the decomposition  $p_*\omega_C^{\otimes 2}$ .

$n-1$	$-1$	$-1$	0	0	0	*	0	0	0	0	0
$n-2$	0	$-1$	0	0	0	*	0	0	0	0	0
$n-3$	0	0	0	0	0	*	0	0	0	0	0
	0	0	1	0	0	*	0	0	0	0	0
	0	0	1	1	0	*	0	0	0	0	0
	*	*	*	*	*	*	*	*	*	*	*
	0	0	1	1	1	*	0	0	0	0	0
3	0	0	1	1	1	*	1	0	0	0	0
2	0	0	1	1	1	*	1	1	0	0	0
1	$-1$	$-1$	0	0	0	*	0	0	0	$-1$	$-1$
0	$-1$	$-1$	0	0	0	*	0	0	0	0	$-1$
	0	1	2	3							$n-1$

Figure: The degrees of  $(p_*\omega_C^{\otimes 2})^{(\alpha,\beta)}$

Note that  $\forall n \geq 4$  the degree is negative only for 10 characters.





# End of the proof of the main theorem

We need then to find six characters such that

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### End of the proof.

We pick the following six characters

$$\begin{array}{lll} \chi_0 = (2, 1) & \chi_1 = (1, 3) & \chi_\infty = (1, 2) \\ \chi'_0 = (4, 1) & \chi'_1 = (3, 1) & \chi'_\infty = (1, 4) \end{array}$$

The only check that is not trivial is that  $H^0(\omega_{\mathcal{C}}^{\otimes 2})^{(\chi')} \neq \{0\}$ : this indeed fails for  $n = 4$  but a tedious computation shows that it holds for  $n \geq 8$ .  $\square$



# Open problems

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*Construct rigid manifolds  $M$  with  $h^1(M, \Theta) = 1$ , resp. arbitrarily high.*



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## Problem (4)

*Construct rigid surfaces to which our criterion does not apply.*

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