

# Rigid but not infinitesimally rigid compact complex manifolds

joint work with I. Bauer (Bayreuth)

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# Overview

## 1 The Question

- Rigidities
- Morrow-Kodaira's question

## 2 Our main results

- Answers in every dimension  $\geq 2$

## 3 Why is that difficult?

- Rigid manifolds
- Manifolds with obstructed deformations
- The construction

## 4 Open problems



# Rigid compact complex manifolds

## Definition

A compact complex manifold  $M$  is *rigid* if for each deformation of  $M$ ,  $f: (\mathfrak{X}, M) \rightarrow (B, b_0)$  there is an open neighbourhood  $U \subset B$  of  $b_0$  such that  $M_t := f^{-1}(t) \cong M$  for all  $t \in U$ .

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The situation in higher dimension is much more complicated: for example the Hirzebruch surface  $\mathbb{F}_2$  is not rigid and homeomorphic to the rigid surface  $\mathbb{P}_{\mathbb{C}}^1 \times \mathbb{P}_{\mathbb{C}}^1$ .



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How do we check the rigidity of a manifold?



# The Kuranishi family

Let  $M$  be a compact complex manifold.

Kuranishi constructed a deformation  $\pi: (\mathcal{X}, M) \rightarrow (\text{Def}(M), 0)$  of  $M$  where  $(\text{Def}(M), 0)$  is a germ of analytic subspace of the vector space<sup>1</sup>  $H^1(M, \Theta)$ , inverse image of the origin under a local holomorphic map, the *Kuranishi map*,  $k: H^1(M, \Theta) \rightarrow H^2(M, \Theta)$  whose differential vanishes<sup>2</sup> at the origin.

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<sup>1</sup>Here  $\Theta$  is the sheaf of holomorphic vector fields on  $M$ .

<sup>2</sup>Then  $H^1(M, \Theta)$  is the Zariski tangent space of  $(\text{Def}(M), 0)$ .

In particular  $(\text{Def}(M), 0)$  is smooth if and only if  $k = 0$ , in which case we say that  $M$  has *unobstructed deformations*.





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## Theorem (Kuranishi)

*The Kuranishi family is semiuniversal, and universal if  $H^0(M, \Theta) = 0$ .*

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## Corollary (Kuranishi's criterion for rigidity)

$M$  *infinitesimally rigid*  $\Rightarrow$   $M$  *rigid*



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## Corollary (Kuranishi's criterion for rigidity)

$$M \text{ infinitesimally rigid} \Rightarrow M \text{ rigid}$$

In particular  $\mathbb{P}_{\mathbb{C}}^1 \times \mathbb{P}_{\mathbb{C}}^1$  is (infinitesimally) rigid.



# Morrow-Kodaira's Problem

Morrow and Kodaira asked if the converse implication also holds<sup>3</sup>:

**THEOREM 3.2.** If  $H^1(M, \Theta) = 0$ , then  $M$  is rigid. We will give a proof of this using elementary methods. We have the following:

**PROBLEM.** Find an example of an  $M$  which is rigid, but  $H^1(M, \Theta) \neq 0$ .  
(Not easy?)

**REMARK.**  $\mathbb{P}^n$  is rigid. For  $n \geq 2$  the only known proof is to show  $H^1(\mathbb{P}^n, \Theta) = 0$  [Bott (1957)]. Let us proceed to the proof.

A solution of the M-K Problem is a manifold  $M$  such that  $\text{Def}(M)$  is a *fat* point, a *singular* point.

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<sup>3</sup>This is a screenshot of the book *Complex Manifolds* by James Morrow and Kunihiko Kodaira (1971), *Holt, Rinehart and Winston, Inc.*



# The main result

## Theorem

For every even  $n \geq 8$  such that  $3 \nmid n$  there is a minimal regular surface  $S_n$  of general type with

$$K_{S_n}^2 = 2(n-3)^2, \quad p_g(S_n) = \left(\frac{n}{2} - 2\right) \left(\frac{n}{2} - 1\right),$$

such that  $S_n$  is rigid, but not infinitesimally rigid:  $h^1(S_n, \Theta) = 6$ .



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The canonical models of these surfaces have exactly 6 singular points, all nodes. The hard part is proving their rigidity, since Kuranishi's rigidity criterion fails.



# Generalization to higher dimension

## Lemma

Let  $M, N$  be compact complex manifolds, such that

$$h^0(M, \Theta)h^1(N, \mathcal{O}) = h^0(N, \Theta)h^1(M, \mathcal{O}) = 0$$

Then  $\text{Def}(M \times N) = \text{Def}(M) \times \text{Def}(N)$ .

Then, if  $M$  is a regular surface of general type solving the M-K Problem and  $N$  is a rigid manifold, by Künneth formula  $M \times N$  is a solution too.





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Then, if  $M$  is a regular surface of general type solving the M-K Problem and  $N$  is a rigid manifold, by Künneth formula  $M \times N$  is a solution too. Using some known rigid manifolds<sup>4</sup> we obtain

## Theorem

There are rigid manifolds of dimension  $d$  and Kodaira dimension  $\kappa$  that are not infinitesimally rigid for all possible pairs  $(d, \kappa)$  with  $d \geq 5$  and  $\kappa \neq 0, 1, 3$  and for  $(d, \kappa) = (3, -\infty), (4, -\infty), (4, 4)$ .

<sup>4</sup>listed in Ingrid Bauer and Fabrizio Catanese, *On rigid compact complex surfaces and manifolds*, *Adv. Math.* **333**, 620–669 (2018).

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Theorem (Ingrid Bauer and Fabrizio Catanese, *On rigid compact complex surfaces and manifolds*, *Adv. Math.* **333**, 620–669 (2018).)

Let  $M$  be a smooth compact complex surface, which is rigid. Then either

- 1  $M$  is a minimal surface of general type, or
- 2  $M$  is a Del Pezzo surface of degree  $d \geq 5$
- 3  $M$  is an Inoue surface of type  $S_M$  or  $S_{N,p,q,r}^-$

Rigid Del Pezzo and Inoue surfaces are infinitesimally rigid, so every surface solving M-K Problem is minimal with Kodaira dimension 2.

How do check rigidity when the Kuranishi criterion fails?



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Burns and Wahl<sup>5</sup> show how to associate to each smooth rational curve  $E$  with  $E^2 = -2$  in a complex surface  $M$  a 1-dimensional subspace  $H_E^1(M)$  of  $H^1(M, \Theta)$ .

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Note that in particular if  $M$  is the minimal resolution of the singularities of a *nodal* surface<sup>6</sup>,  $M$  can't be infinitesimally rigid.

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<sup>6</sup>A nodal surface is a singular surface whose singular points are nodes, locally the quotient of a 2-dimensional disc by  $p \mapsto -p$ .



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The minimal model of any rigid surface of general type whose canonical model is singular does the job.

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# The Kas formula

A necessary condition for  $M$  to be rigid is that it is obstructed along this line:  $H_E^1(M) \not\subset \text{Def}(M)$ . A way to check it has been provided by Kas.



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Let  $\theta$  be a generator of  $H_E^1(M) \subset H^1(M, \Theta)$  and write

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Kas provides an explicit way to compute  $\alpha(\eta)$  for all  $\eta \in H^0(M, \Omega^1 \otimes \Omega^2)$ .

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# A criterion to prove rigidity

The main tool for the proof of the first theorem is the following rigidity criterion for *nodal* surfaces.

## Theorem

Let  $M$  be the minimal res. of the sing. of a nodal surface  $X$ . Assume that

- 1  $H^1(X, \Theta) = 0$ ;
- 2 the elements  $\alpha_{\nu_i} \in H^2(M, \Theta)$  associated to the nodes  $\nu_i$  of  $X$  as in the discussion of the Kas formula are linearly independent in  $H^0(M, \Omega^1 \otimes \Omega^2)^\vee$ .

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Then  $M$  is rigid and  $h^1(M, \Theta)$  equals the number of nodes of  $X$ .

Note that if  $X$  has at least a node, then  $M$  is not infinitesimally rigid.



# The Fermat curves

The Fermat curve of degree  $n$ ,  $C := \{\sum_{j=0}^2 x_j^n = 0\} \subset \mathbb{P}_{\mathbb{C}}^2$  admits a natural action of the group  $G \cong (\mathbb{Z}/n\mathbb{Z})^2$ :

$$(a_1, a_2)(x_0 : x_1 : x_2) = (x_0 : e^{a_1 \frac{2\pi i}{n}} x_1 : e^{a_2 \frac{2\pi i}{n}} x_2).$$



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This  $G$ -action has only three orbits of cardinality different by  $n^2$ , all of cardinality  $n$ :

- $C \cap \{x_0 = 0\}$  with stabilizer  $\langle(1, 1)\rangle \cong \mathbb{Z}/n\mathbb{Z}$
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By Hurwitz formula  $C/G \cong \mathbb{P}^1$ .



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In fact  $S_4$  is a numerical Campedelli surface with fundamental group  $(\mathbb{Z}/2\mathbb{Z})^3$ : these are well known, their Kuranishi family has dimension 6.



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## Problem (4)

*Construct rigid surfaces to which our criterion does not apply.*

# References

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