Dynamical vector fields on the manifold of quantum states

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To describe any physical system we need to identify:

- States
- Observables
- Probability function
- Evolution equation
- Composition rule of systems

Classical systems

A symplectic manifold (\mathcal{M}, ω)

States: probability distibutions or probability measures, Liouville measure, comparison measure

Observables: $\mathcal{F}(\mathcal{M}, \mathbb{R})$

Probability function: for any Borelian $\mathcal{B} \subseteq \mathbb{R}$, ρ a state, f observable: $\int_{f^{-1}(\mathcal{B})} \rho \, \mathrm{d}\mu_L \ = \ \frac{\text{Probability to find a value of fin B when the system}}{\text{is in the state } \rho}$

Evolution: $i_{\Gamma}\omega = -\mathrm{d}H$ $\frac{\mathrm{d}}{\mathrm{d}t}f = \{H\,,f\}$ $\frac{\mathrm{d}}{\mathrm{d}t}\rho = \{\rho\,,H\}$

Composition: $(\mathcal{M}_1 \times \mathcal{M}_2, \omega_1 \oplus \omega_2)$

Quantum systems

(Schrödinger picture) "wave mechanics": H complex separable Hilbert space

(Pure) States: rays in \mathcal{H} , $\mathcal{P}\mathcal{H}$ complex projective space, Hilbert manifold $\rho_{\psi} = \frac{|\psi\rangle\langle\psi|}{\langle\psi|\psi\rangle}$

Observables: real elements in $\mathcal{B}(\mathcal{H}) \longleftrightarrow \mathcal{H} \otimes \mathcal{H}^*$

Probability function: for any res. of the identity $\sum_{j} |e_{j}\rangle\langle e_{j}| = \mathbb{I}$, $\int |x\rangle dx\langle x|$ and any vector $|\psi\rangle$, $p_{j}(\psi) = \frac{\langle e_{j}|\psi\rangle\langle\psi|e_{j}\rangle}{\langle\psi|\psi\rangle}$, $p_{j} \geq 0$, $\sum_{j} p_{j} = 1$ similarly $\psi^{*}(x)\psi(x) = \frac{\langle x|\psi\rangle\langle\psi|x\rangle}{\langle\psi|\psi\rangle}$, $\psi^{*}(x)\psi(x) \geq 0$, $\int \psi^{*}(x)\psi(x)dx = 1$

similarly $\psi(x)\psi(x) = \frac{1}{\langle \psi | \psi \rangle}$, $\psi(x)\psi(x) \geq 0$, $\int \psi(x)\psi(x)dx = \frac{1}{\langle \psi | \psi \rangle}$

Evolution: $i\hbar \frac{\mathrm{d}}{\mathrm{d}t} |\psi\rangle = \mathbf{H} |\psi\rangle \Rightarrow i\hbar \frac{\mathrm{d}}{\mathrm{d}t} \rho_{\psi} = [\mathbf{H}, \rho_{\psi}]$

Composition: $\mathcal{H}_{12} = \mathcal{H}_1 \otimes \mathcal{H}_2$

Quantum systems

(Heisenberg picture) "matrix mechanics": a C*-algebra A

Observables: real elements in $A: A = A^{\dagger}$

States: normalized, positive, linear functionals on A

$$\rho(\mathbb{I}) = 1, \ \rho(\mathbf{A}^{\dagger}\mathbf{A}) \ge 0, \ \rho(\mathbf{A} + \mathbf{B}) = \rho(\mathbf{A}) + \rho(\mathbf{B})$$

GNS construction gives back a Hilbert space \mathcal{H}_{GNS}

Probability function:

$$\mathbf{E}_j^\dagger = \mathbf{E}_j \in \mathcal{A} \,, \,\, \sum_j \mathbf{E}_j = \mathbb{I} \,, \,\, \mathbf{E}_j \cdot \mathbf{E}_k = \delta_{jk} \mathbf{E}_j \,, \,\,
ho(\mathbf{E}_j) = p_j(
ho) \geq 0 \,, \,\, \sum_j p_j(
ho) = 1$$

Evolution:
$$i\hbar \frac{\mathrm{d}}{\mathrm{d}t}\mathbf{A} = [\mathbf{A}, \mathbf{H}], \quad i\hbar \frac{\mathrm{d}}{\mathrm{d}t}\rho = [\mathbf{H}, \rho]$$

Composition: $A_{12} = A_1 \otimes A_2$

Quantum systems

Other pictures:

Weyl-Wigner

• Generalized coherent states

• Tomographic picture

• Linearity versus nonlinearity

Probabilistic-statistical interpretation of quantum mechanics. The primary object is the space of states (we shall consider only finite-dimensional systems).

Schrödinger-Dirac picture: The Hilbert manifold of pure states.

Heisenberg, Born-Jordan: A connected closed complete and convex set S in some affine topological space E.

The space of states is a stratified manifold (the boundary is not a smooth manifold) with two compatible contravariant tensor fields:

A Skew-symmetric, defines a Poisson bracket

R Symmetric, defines a Jordan algebra

Observables are real-valued functions on S with the following properties:

 $\Lambda(\mathrm{d}f)=X_f$ Hamiltonian vector fields with the Killing property $L_{X_f}\mathcal{R}=0$ $\mathcal{R}(\mathrm{d}f)=Y_f$ Gradient vector fields

Hamiltonian and gradient vector fields generate the tangent bundle of S, for every stratum, and close on the Lie algebra of $SL(N,\mathbb{C})$

We find that:

- Observables constitute a Lie-Jordan algebra;
- By extension to complex-valued combinations of observables we generate a C*-algebra.

By using a GNS construction we recover a Hilbert space.

The irriducibility requirement (a minimality condition) allows to recover the Hilbert space of the Schrödinger-Dirac picture

Example: Q-bit

States, Bloch ball in $E = \mathbb{R}^3 \subset \mathbb{R}^4$

$$\rho = \frac{1}{2} \left(\sigma_0 + \vec{x} \cdot \vec{\sigma} \right) \qquad \mathcal{S} = \left\{ \vec{x} \colon |\vec{x}|^2 \le 1 \right\}$$

$$\Lambda = \frac{\epsilon_l^{jk} x^j}{2} \frac{\partial}{\partial x^k} \wedge \frac{\partial}{\partial x^l} \qquad \mathcal{R} = \left(\delta^{jk} - x^j x^k\right) \frac{\partial}{\partial x^j} \otimes \frac{\partial}{\partial x^k}$$

Observables $f = a_j x^j, \ a_j \in \mathbb{R}$

$$X_f = \epsilon_l^{jk} a_k x^l \frac{\partial}{\partial x^j}, \quad Y_f = a_j \frac{\partial}{\partial x^j} - (a_k x^k) \left(x^j \frac{\partial}{\partial x^j} \right)$$

They generate the Lie algebra of $SL(2\,,\mathbb{C})$

If we consider a realization of the Lie algebra in terms of matrices we get back the complex matrix algebra generated by σ_0 , σ_1 , σ_2 , σ_3

Example: Q-bit

The Lie-Jordan algebra:

$$\{x^j, x^k\} = \Lambda(\mathrm{d}x^j, \mathrm{d}x^k) = \epsilon_l^{jk} x^l$$

$$x^j \odot x^k = \mathcal{R}(\mathrm{d}x^j, \mathrm{d}x^k) + x^j x^k \Rightarrow x^j \odot x^j = 1, \ x^j \odot x^k = 0$$

We can define $x^j \star x^k = x^j \odot x^k + i\{x^j, x^k\}$ so that:

$$x^{j} \odot x^{k} = \frac{1}{2} \left(x^{j} \star x^{k} + x^{k} \star x^{j} \right) , \quad \{ x^{j}, x^{k} \} = -\frac{\imath}{2} \left(x^{j} \star x^{k} - x^{k} \star x^{j} \right)$$

Example: Q-bit

Remark: since we are using tensor fields, we are free to perform every nonlinear change of coordinates. The convexity is hidden. For instance, in spherical coordinates we have:

$$\Lambda = \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} \otimes \frac{\partial}{\partial \varphi} \qquad \mathcal{R} = (1 - r^2) \frac{\partial}{\partial r} \otimes \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial \theta} \otimes \frac{\partial}{\partial \theta} + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \varphi} \otimes \frac{\partial}{\partial \varphi}$$

It is clear by inspection that Hamiltonian and gradient vector fields are tangent to the sphere of pure states, r=1.

The interior of the ball is an orbit of $SL(2,\mathbb{C})$

S is generated by $r\cos\theta$, $r\sin\theta\sin\varphi$, $r\sin\theta\cos\varphi$ by means of \mathcal{R} , Λ

Let us consider the Kossakowski-Lindblad equation:

$$\frac{\mathrm{d}}{\mathrm{d}t}\rho = \mathbf{L}(\rho), \quad \rho(t=0) = \rho_0$$

$$\mathbf{L}(\rho) = -i \left[\mathbf{H}, \rho \right] + \frac{1}{2} \sum_{j} \left(\left[\mathbf{v}_{j} \rho, \mathbf{v}_{j}^{\dagger} \right] + \left[\mathbf{v}_{j}, \rho \mathbf{v}_{j}^{\dagger} \right] \right) =$$

$$= -i \left[\mathbf{H}, \rho \right] - \frac{1}{2} \sum_{j} \left[\mathbf{v}_{j}^{\dagger} \mathbf{v}_{j}, \rho \right]_{+} + \sum_{j} \mathbf{v}_{j} \rho \mathbf{v}_{j}^{\dagger}$$

say with
$$Tr(\mathbf{v}_j) = 0$$
, $Tr(\mathbf{v}_j^{\dagger} \mathbf{v}_k) = 0$ if $j \neq k$

We see immediately that the equations of motion split into:

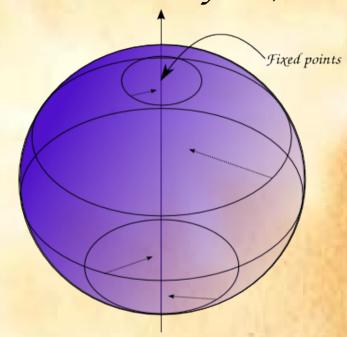
- Hamiltonian term;
- Symmetric term;
- Kraus term.

It is possible to write a vector field with this equation of motion. It turns out that the one associated with the Kraus term is a nonlinear vector field, similar to the nonlinear vector field associated with the symmetric tensor (the gradient vector field).

Example: the phase-damping of a q-bit

$$\mathbf{L}(\rho) = -\gamma \left(\sigma_3 \rho \,\sigma_3 - \rho\right)$$

$$Z_L = -2\gamma \left(x^1 \frac{\partial}{\partial x^1} + x^2 \frac{\partial}{\partial x^2} \right)$$



The "miracle" of the Kossakowski-Lindblad equation is that the two nonlinearities camcel each other so that the resulting vector field is actually linear!

Summarizing

- On the space of quantum states, Hamiltonian and gradient vector fields generate the action of a Lie group: $SL(\mathcal{H}\,\mathbb{C})$
- To describe semigroups we have to introduce Kraus vector fields.
- Having described the dynamics in terms of vector fields will provide a framework to describe non-Markovian dynamics.
- The tensorial description allows for generic nonlinear transformations, hopefully more flexible to deal with nonlinearities, like entanglement, entropies and so on.